

# FOD-BOT

Autonomous FOD Sweeping System



- 24/7/365 day and night
- Unattended operation
- Multi-mission chassis

# SYSTEMATIC & SAFE

- Obstacle detect & avoid
- Preplanned routes
- NDAA compliant hardware

# **ANYTIME & ANYWHERE**

- All weather and waterproof
- Operable in extreme temperatures
- Can be palletized to ship

MANAGEMENT | NOTIFICATIONS | DATA ANALYTICS

# TECHNICAL INFORMATION

FOD Collection Size Maximum Speed Maximum Incline

Operating Time

Charging Time

Operational Temperature

Collision Avoidance

0.02" to 8"

5.6 mph (2.5 m/s)

Up to 26.5° (50% grade)

Up to 6 hrs on a single charge

2.0 hours (30 min from 30-80%)

-4° F To 104° F (-20° C To 40° C)

Ultrasound and LiDAR sensors





# **Technical Specifications**

## **Software**

## **ONBOARD SYSTEMS (EDGE)**

#### **Essential Core**

Autonomy stack running directly on the FOD-BOT, enabling full mission independence without network reliance. Fuses LiDAR, GPS, and vision data for perception, navigation, and adaptive path planning.

- Real-time perception and object classification
- GNSS/RTK and LiDAR navigation and dynamic replanning
- Full autonomy cycle: deploy  $\rightarrow$  sweep  $\rightarrow$  return  $\rightarrow$  self-charge  $\rightarrow$  self-dispose
- Redundant safety and override systems

#### Safety & Compliance

Built-in multi-layer safety architecture meeting FAA and airside standards.

Onboard systems maintain situational awareness and safe behavior.

- 360° LiDAR obstacle detection
- Dual E-Stop and remote override protocols
- · Geofencing and virtual safety zones

#### **Onboard Operator Interface**

Touchscreen control for single-robot missions, diagnostics, and overrides.

- Local start/stop and manual control
- · Live system health display

### **CLOUD & FLEET SYSTEMS**

#### **Essential Ops Supervisor**

Fleet-management layer hosted in the Essential Aero cloud ecosystem. Provides real-time mission visibility, scheduling, and analytics for all connected robots across multiple sites.

- Live mission tracking and remote dispatch
- · Multi-robot coordination and zone scheduling
- Automated uptime, mission, and FOD collection reports
- Remote alerts, overrides, and maintenance notifications
- Cloud-linked data storage for analytics and ROI evaluation

#### **Essential Commander**

Browser-based control hub (desktop and mobile) unifying all connected FOD-BOTs and site infrastructure. Provides intuitive mission planning, data visualization, and remote supervision.

- · Point-and-click mission setup and map editing
- Real-time telemetry and system health monitoring
- Fleet dashboards for analytics and compliance review
- Intuitive user interface optimized for airside operations

#### **Hardware**

#### **Accessories and Attachments**

Autonomy	Wireless charger
	Diamagal akakian

Disposal station
Surface Cleaning FOD-MAT

Track-Sweep

Attachment Interface 2" Ball hitch

**Dimensions and Weight** 

External Dimensions  $3.6 \times 2 \times 2.6 \text{ ft (L x W x H)}$ 

Wheel Diameter 1 ft

Weight 150 lbs

**Speed and Performance** 

Maximum Speed 5.6 mph (3.5 m/s)

Maximum Incline 50%

(Without Payload)

Chassis 4-wheel robot frame

Motor Type 4 hub motors (500W each)

**Power** 

Battery Type Lithium Iron Phosphate (LFP)

Operating Time Up to 6 hours
Charging Time 2.0 hours at 220V

## **Safety Features**

Collision Avoidance Bumper Bar

E-Stop Immediately stop droid in

place

**Environment** 

Operational Temperature -4° F to 104° F

-20° C to 40° C

**Interface and Communication** 

External Communication Redundant 5G router with

Dual-band WiFi, UHF

I/O RJ45 Ethernet, USB-A

**Sensors** 

GPS Differential GPS with RTK

LiDAR 360 degrees 3D LiDAR

